Relationships required for Physics Advanced Higher

$$v = \frac{ds}{dt}$$

$$a = \frac{dv}{dt} = \frac{d^2s}{dt^2}$$

$$v = u + at$$

$$s = ut + \frac{1}{2}at^2$$

$$v^2 = u^2 + 2as$$

$$\omega = \frac{d\theta}{dt}$$

$$\alpha = \frac{d\omega}{dt} = \frac{d^2\theta}{dt^2}$$

$$\omega = \omega_o + \alpha t$$

$$\omega^2 = {\omega_o}^2 + 2\alpha\theta$$

$$\theta = \omega_o t + \frac{1}{2}\alpha t^2$$

$$s = r\theta$$

$$v = r\omega$$

$$a_t = r\alpha$$

$$\omega = \frac{2\pi}{T}$$

$$\omega = 2\pi f$$

$$a_r = \frac{v^2}{r} = r\omega^2$$

$$F = \frac{mv^2}{r} = mr\omega^2$$

$$I = \sum mr^2$$

$$\tau = Fr$$

$$\tau = I\alpha$$

$$L = mvr = mr^2\omega$$

$$L = I\omega$$

$$E_{k(rotational)} = \frac{1}{2}I\omega^2$$

$$E_P = E_{k(translational)} + E_{k(rotational)}$$

$$F = \frac{GMm}{r^2}$$

$$F = \frac{GMm}{r^2} = \frac{mv^2}{r} = mr\omega^2 = mr\left(\frac{2\pi}{T}\right)^2$$

$$V = -\frac{GM}{r}$$

$$E_P = Vm = -\frac{GMm}{r}$$

$$v_{esc} = \sqrt{\frac{2GM}{r}}$$

$$r_{Schwarzschild} = \frac{2GM}{c^2}$$

$$b = \frac{L}{4\pi d^2}$$

$$\frac{P}{A} = \sigma T^4$$

$$L = 4\pi r^2 \sigma T^4$$

$$E = hf$$

$$mvr = \frac{nh}{2\pi}$$

$$\lambda = \frac{h}{p}$$

$$\Delta x \, \Delta p_x \geq \frac{h}{4\pi}$$

$$\Delta E \, \Delta t \geq \frac{h}{4\pi}$$

$$F = qvB$$

$$F = \frac{mv^2}{r}$$

$$F = -ky$$

$$\omega = 2\pi f = \frac{2\pi}{T}$$

$$a = \frac{d^2 y}{dt^2} = -\omega^2 y$$

$y = A\cos\omega t$ or $y = A\sin\omega t$

$$v = \pm\omega\sqrt{\left(A^2 - y^2\right)}$$

$$E_k = \frac{1}{2}m\omega^2\left(A^2 - y^2\right)$$

$$E_P = \frac{1}{2}m\omega^2 y^2$$

$$E = kA^2$$

$$y = A\sin 2\pi\left(ft - \frac{x}{\lambda}\right)$$

$$\phi = \frac{2\pi x}{\lambda}$$

$$opd = n \times gpd$$

$opd = m\lambda$ or $\left(m + \frac{1}{2}\right)\lambda$ where $m = 0,1,2\ldots$

$$\Delta x = \frac{\lambda l}{2d}$$

$$d = \frac{\lambda}{4n}$$

$$\Delta x = \frac{\lambda D}{d}$$

$$n = \tan i_P$$

$$F = \frac{Q_1 Q_2}{4\pi\varepsilon_o r^2}$$

$$V = \frac{Q}{4\pi\varepsilon_o r}$$

$$E = \frac{Q}{4\pi\varepsilon_o r^2}$$

$$F = QE$$

$$V = Ed$$

$$W = QV$$

$$E_k = \frac{1}{2}mv^2$$

$$B = \frac{\mu_o I}{2\pi r}$$

$$F = IlB\sin\theta$$

$$F = qvB$$

$$\tau = RC$$

$$X_C = \frac{V}{I}$$

$$X_C = \frac{1}{2\pi fC}$$

$$\varepsilon = -L\frac{dI}{dt}$$

$$E = \frac{1}{2}LI^2$$

$$X_L = \frac{V}{I}$$

$$X_L = 2\pi fL$$

$$c = \frac{1}{\sqrt{\varepsilon_o\mu_o}}$$

$$\Delta W = \sqrt{\Delta X^2 + \Delta Y^2 + \Delta Z^2}$$

$$\frac{\Delta W}{W} = \sqrt{\left(\frac{\Delta X}{X}\right)^2 + \left(\frac{\Delta Y}{Y}\right)^2 + \left(\frac{\Delta Z}{Z}\right)^2}$$

$$\left(\frac{\Delta W^n}{W^n}\right) = n\left(\frac{\Delta W}{W}\right)$$

$d = \bar{v}t$

$s = \bar{v}t$

$v = u + at$

$s = ut + \frac{1}{2}at^2$

$v^2 = u^2 + 2as$

$s = \frac{1}{2}(u + v)t$

$W = mg$

$F = ma$

$E_W = Fd$

$E_P = mgh$

$E_K = \frac{1}{2}mv^2$

$P = \frac{E}{t}$

$p = mv$

$Ft = mv - mu$

$F = G\frac{Mm}{r^2}$

$t' = \frac{t}{\sqrt{1 - \left(\frac{v}{c}\right)^2}}$

$l' = l\sqrt{1 - \left(\frac{v}{c}\right)^2}$

$f_o = f_s\left(\frac{v}{v \pm v_s}\right)$

$z = \frac{\lambda_{observed} - \lambda_{rest}}{\lambda_{rest}}$

$z = \frac{v}{c}$

$v = H_0 d$

$W = QV$

$E = mc^2$

$E = hf$

$E_K = hf - hf_0$

$E_2 - E_1 = hf$

$T = \frac{1}{f}$

$v = f\lambda$

$d\sin\theta = m\lambda$

$n = \frac{\sin\theta_1}{\sin\theta_2}$

$\frac{\sin\theta_1}{\sin\theta_2} = \frac{\lambda_1}{\lambda_2} = \frac{v_1}{v_2}$

$\sin\theta_c = \frac{1}{n}$

$I = \frac{k}{d^2}$

$I = \frac{P}{A}$

$V_{peak} = \sqrt{2}V_{rms}$

$I_{peak} = \sqrt{2}I_{rms}$

$Q = It$

$V = IR$

$P = IV = I^2R = \frac{V^2}{R}$

$R_T = R_1 + R_2 + \ldots$

$\frac{1}{R_T} = \frac{1}{R_1} + \frac{1}{R_2} + \ldots$

$E = V + Ir$

$V_1 = \left(\frac{R_1}{R_1 + R_2}\right)V_S$

$\frac{V_1}{V_2} = \frac{R_1}{R_2}$

$C = \frac{Q}{V}$

$E = \frac{1}{2}QV = \frac{1}{2}CV^2 = \frac{1}{2}\frac{Q^2}{C}$

path difference $= m\lambda$ or $\left(m + \frac{1}{2}\right)\lambda$ where $m = 0, 1, 2\ldots$

random uncertainty $= \dfrac{\text{max. value} - \text{min. value}}{\text{number of values}}$